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# Analysis of Nonstationary Vibroacoustic Flight Data Using a Damage-Potential Basis

Presented by

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  - Sheldon Rubin, Christian Lalanne
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# Background

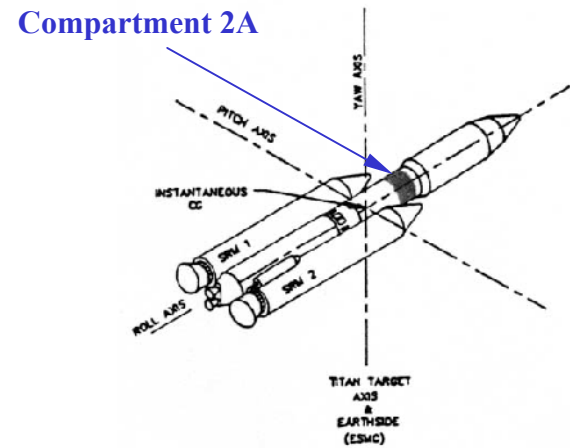
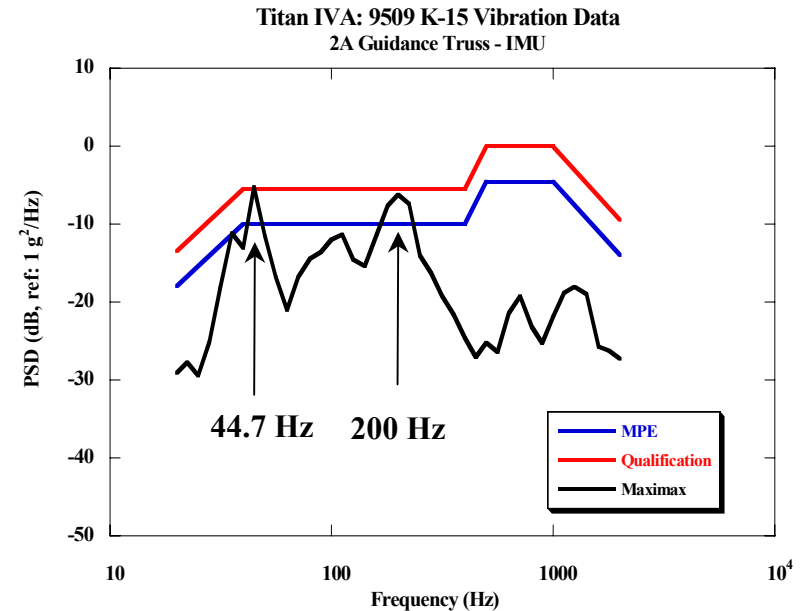
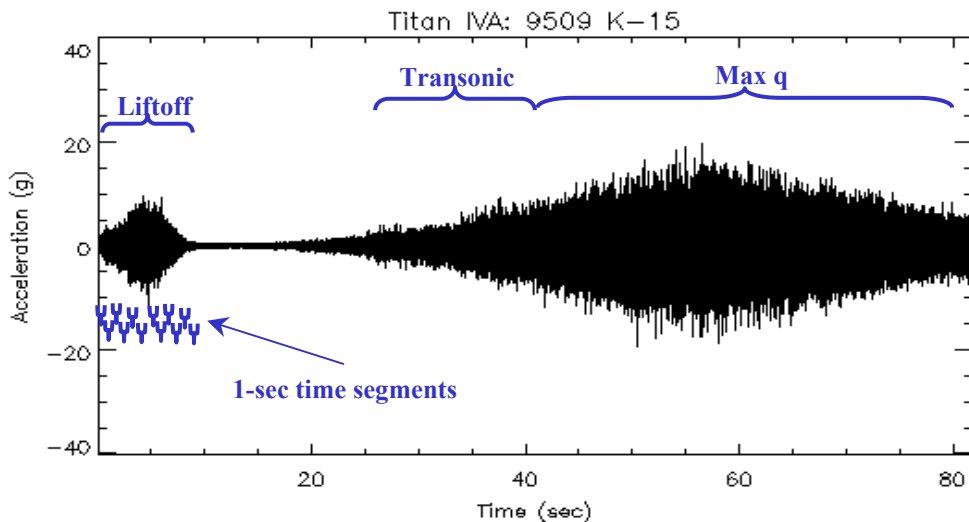
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- Launch/space vehicle equipment subjected to complex, nonstationary (time-varying) flight environments
- Development, qualification, and acceptance test specifications developed from historical data and analytical/empirical techniques
- Testing performed using stationary (constant in time) random or sinusoidal excitation
- Qualification status reassessed after mission by comparing flight data with prior test

Need: Consistent, quantitative and accurate means for characterization and comparison of nonstationary flight and stationary test environments

# Historical Maximax Approach

- Flight data treated as series of overlapping stationary time segments
- Determine power spectral density (PSD) during each time segment
- Retain maximum value of spectrum at each frequency independently and loop on number of time segments
- Compare maximax PSD with test specification



# Maximax Limitations

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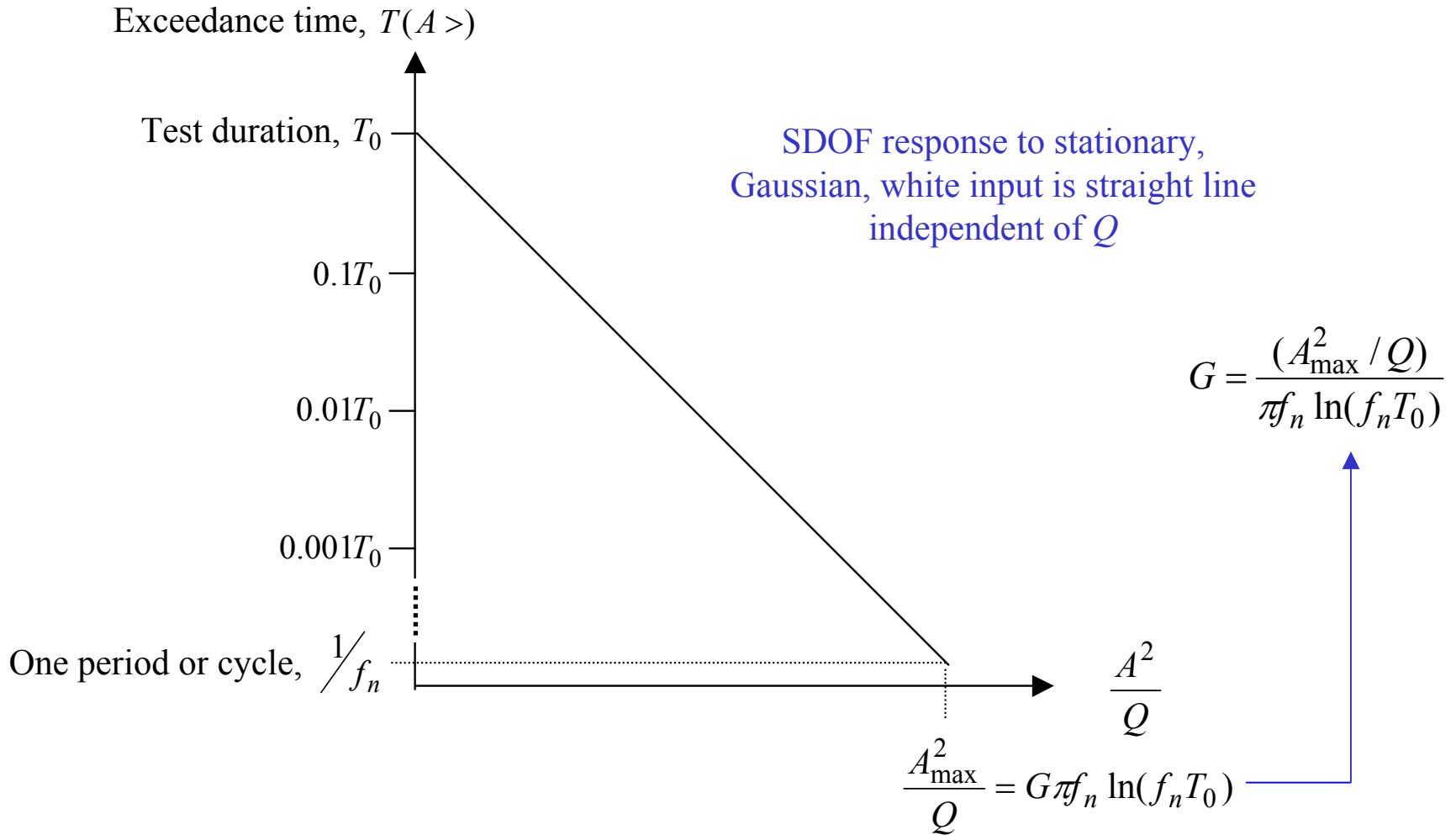
- Fatigue failure mechanism not addressed
- Processing errors due to assumption of stationarity within each time segment
  - Peak responses in flight data can be considerably overestimated
    - Excessive conservatism in specification definition and consequent impact on testing techniques (more cost, less reliability)
    - After early missions, can cause inappropriate consideration/implementation of component re-qualification or other vibration reduction techniques (cost, schedule impact)
- Results dependent upon choice of processing parameters
  - i.e. record length, spectral bandwidth, number of averages
    - Not related to physical properties of system such as modal quality factor (damping)

# Stationary Random Test Basics

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- Test duration  $T_0$  and magnitude  $G$
- SDOF response has Rayleigh distribution of peaks
- Probability of cycles with amplitude  $> A$ :  $P(A >) = e^{-A^2/2\sigma^2}$
- Time response cycles  $> A$ :  $T(A >) = T_0 P(A >) = T_0 e^{-A^2/2\sigma^2}$
- SDOF mean-square response:  $\sigma^2 \cong \frac{\pi}{2} G f_n Q$
- Yields:  $\ln[T_0 / T(A >)] = \frac{1}{\pi G f_n} \frac{A^2}{Q}$
- Plot of  $\log[T(A >)]$  vs. linear  $A^2 / Q$  is a straight line

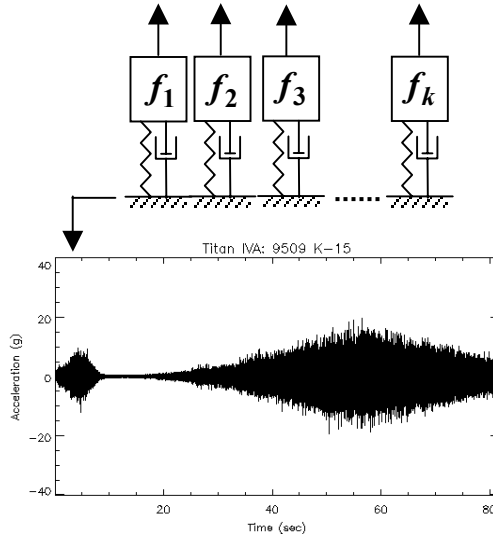
# Plot for Stationary Test (for each $f_n$ )



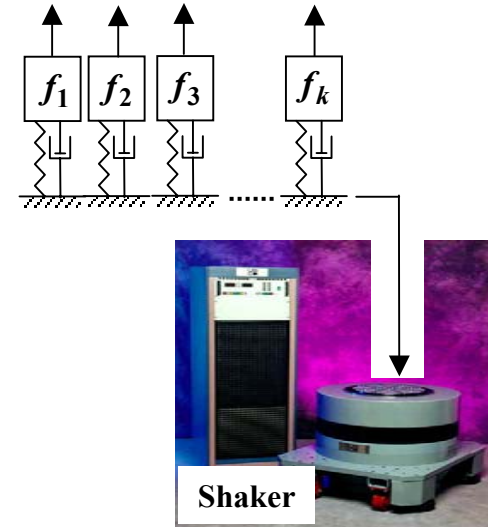
# Damage Potential Comparison

## SDOF oscillator response is basis for comparison

Flight



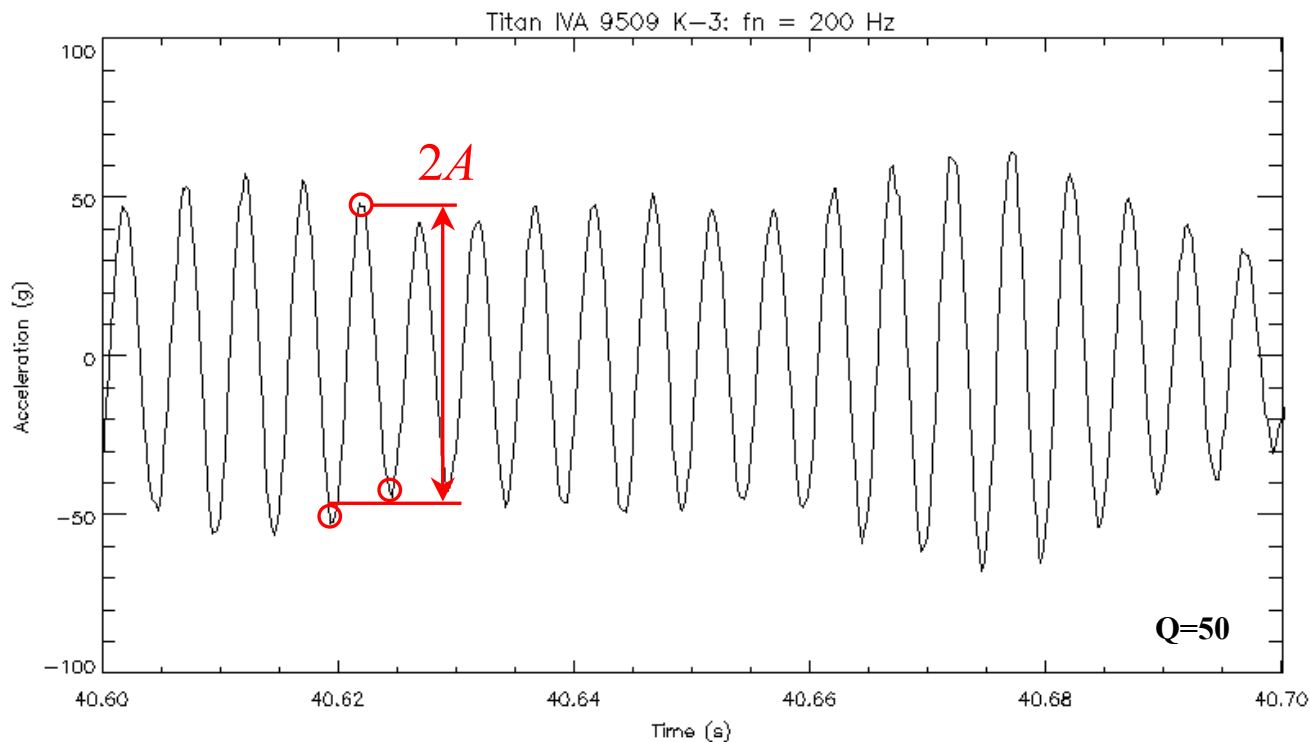
Test



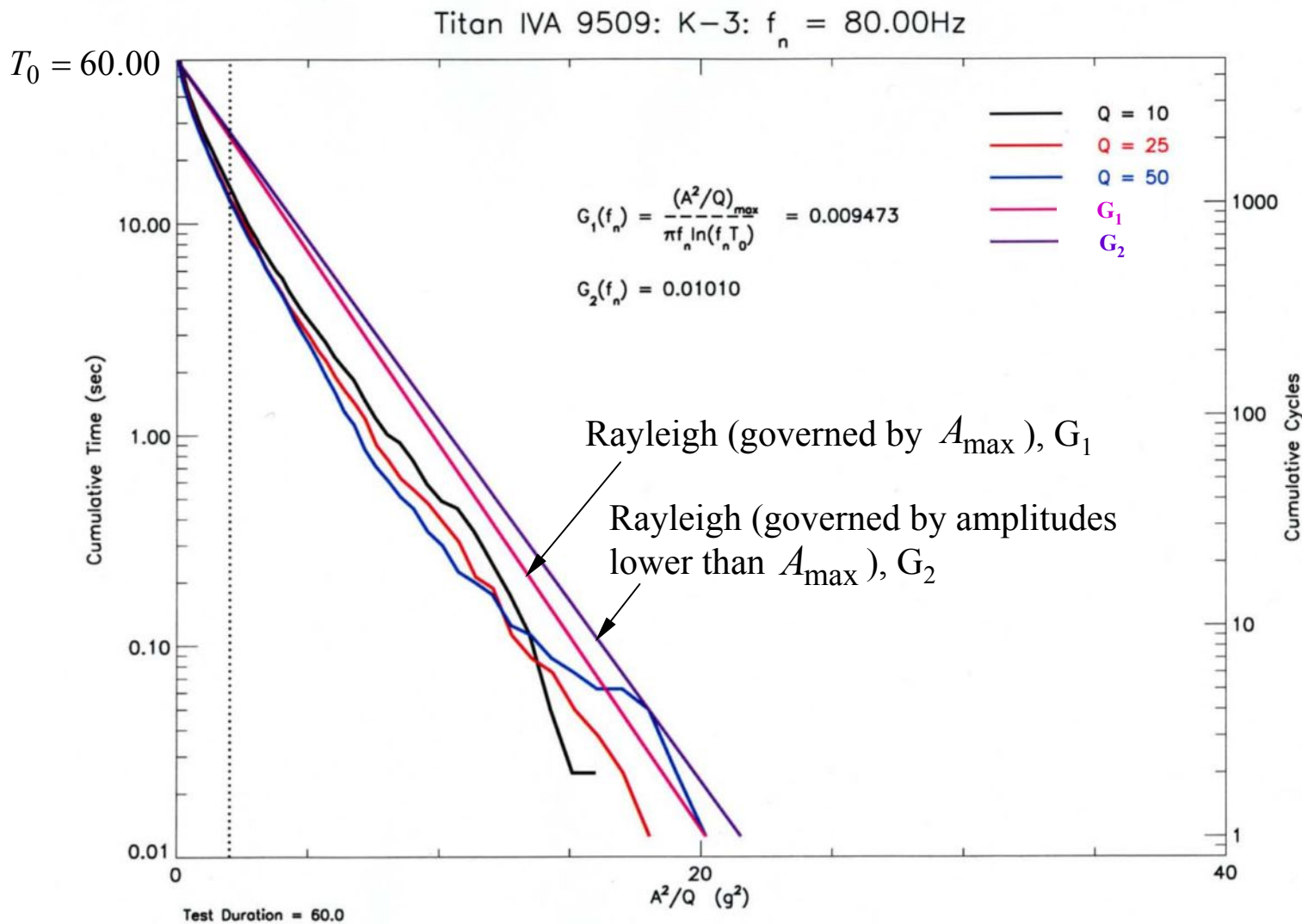
- Apply flight data as input to series of SDOF oscillators
  - 1/12<sup>th</sup>-octave spacing, range of Q (10,25,50)
- For each  $f_n$  and  $Q$ , determine SDOF response and count cycles  $N(A >)$  for which amplitude  $A$  is exceeded
- For SDOF narrowband response,  $T(A >) = \frac{N(A >)}{f_n}$
- Plot  $\log[T(A >)]$  vs. linear  $A^2 / Q$
- For a test duration  $T_0$ , if results for test envelop all flight data, damage potential of test exceeds that of flight
  - Number of cycles in test exceeds number of cycles in flight for all amplitudes
  - Both maximum response and fatigue aspects covered

# Cycle Counting Process

- Cycle of oscillation defined to occur between pair of minima
- Double amplitude equal to value of intermediate maximum minus average of minima
- For narrowband response with zero mean, this is meaningful for evaluating fatigue accumulation



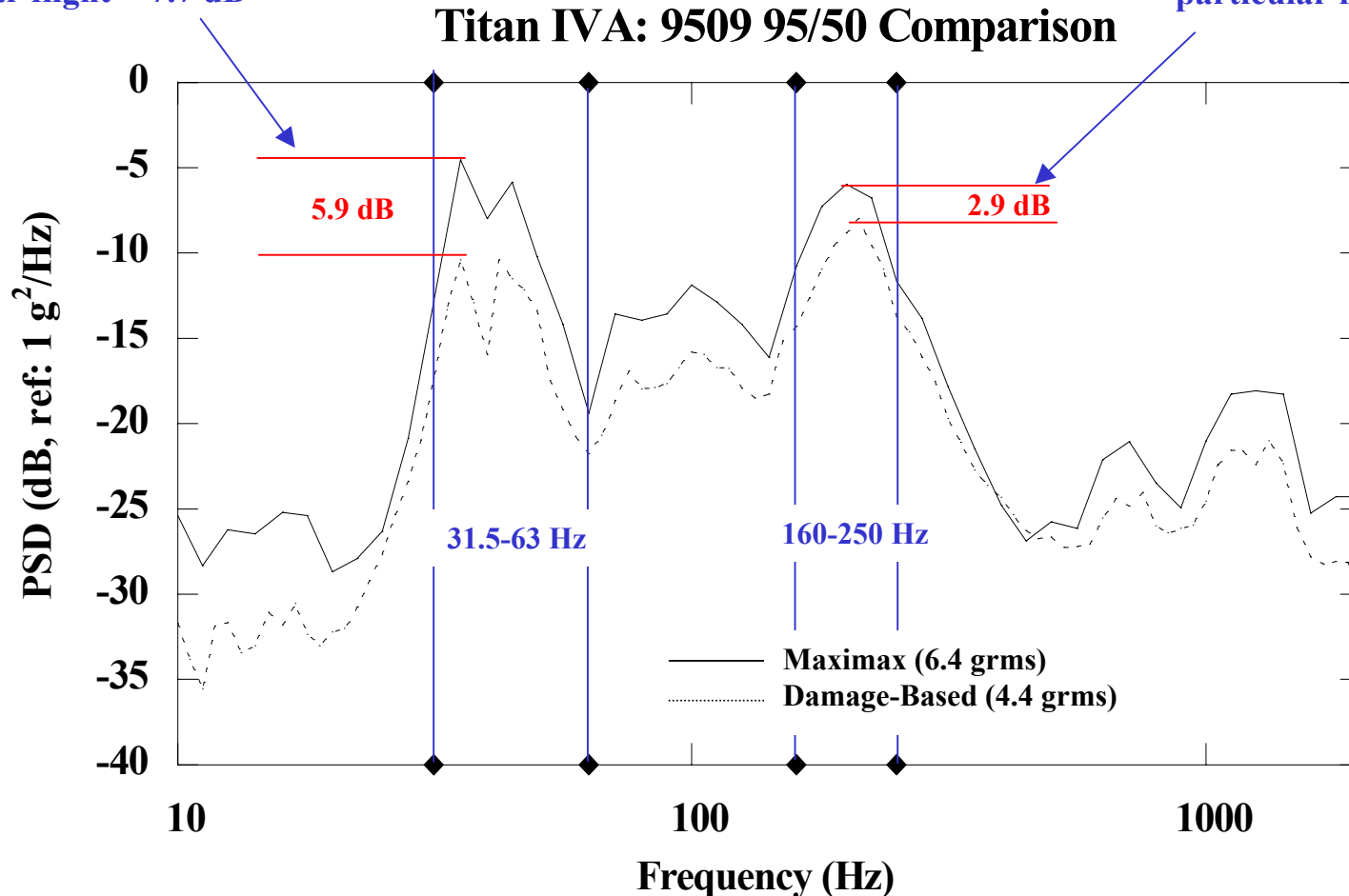
# Example Cycle Count Plot



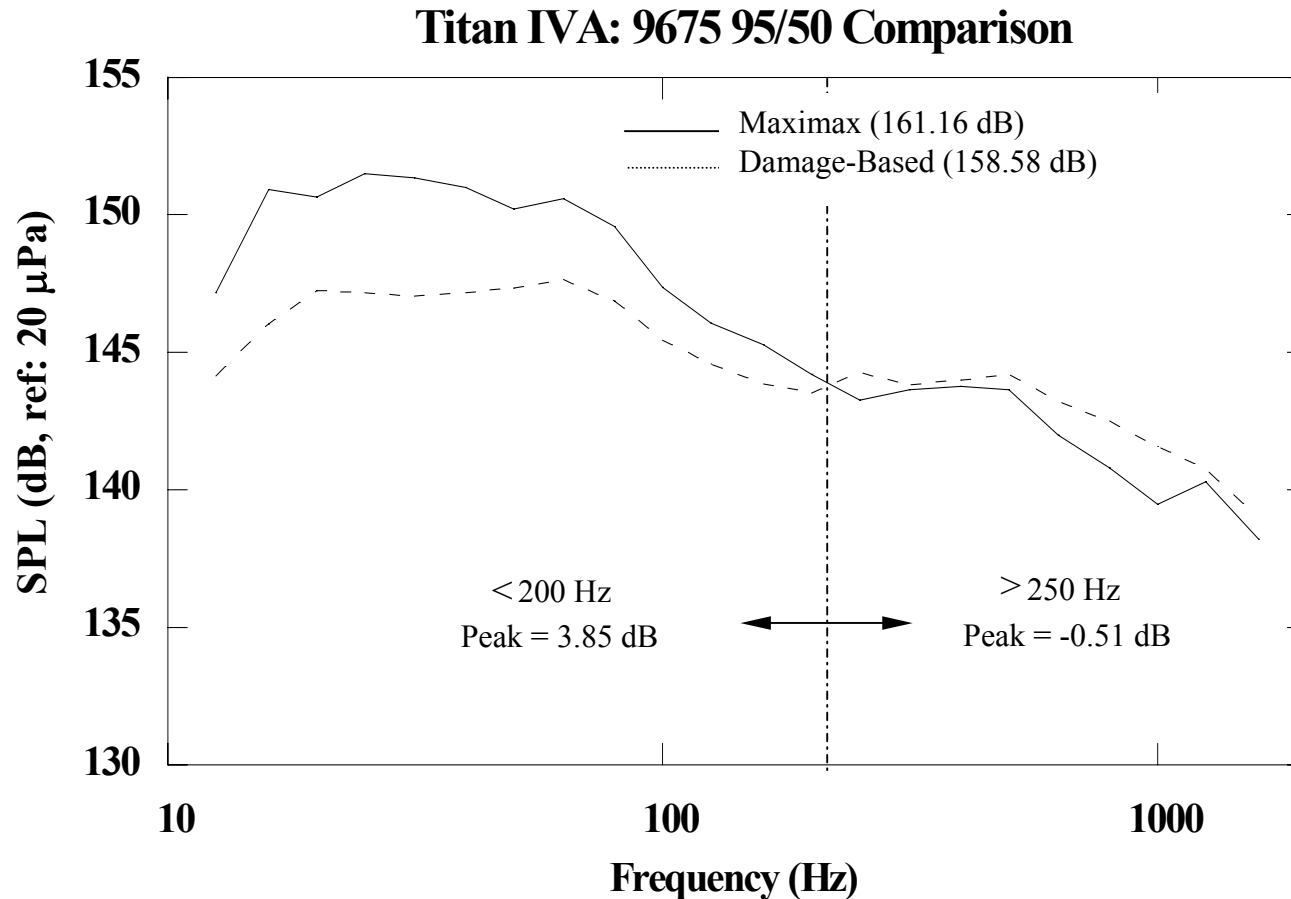
# Comparison of Vibration Results (12 flights)

Max difference on particular flight = 7.7 dB

Max difference on particular flight = 3.71

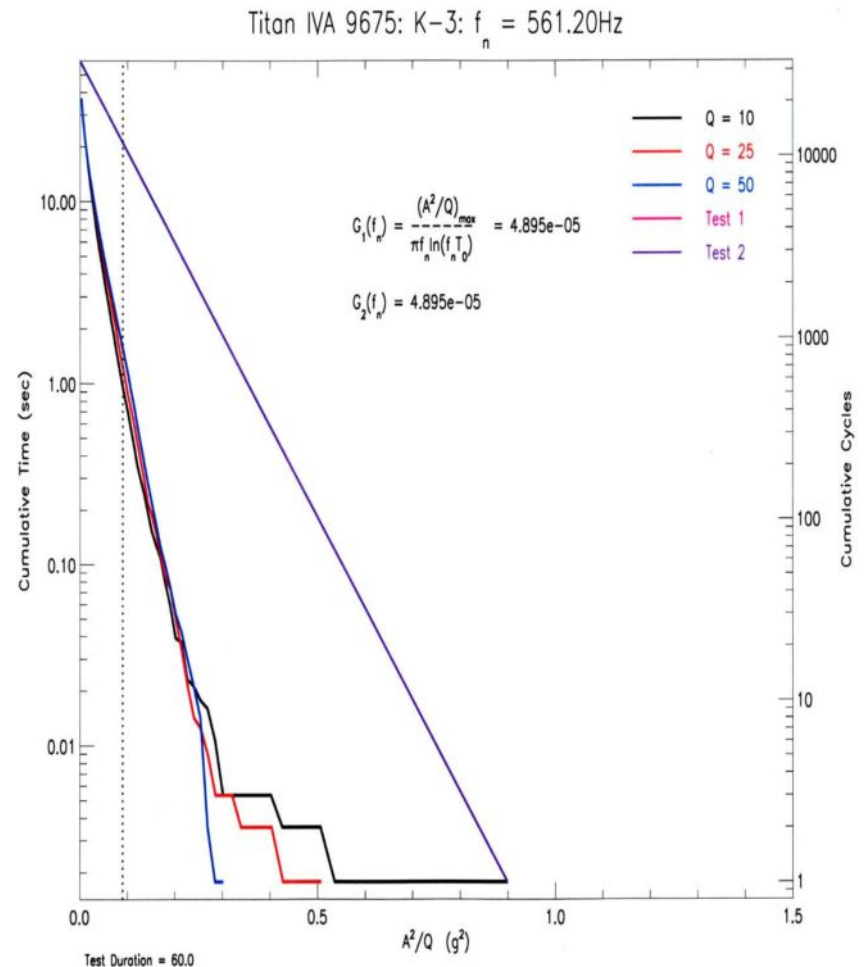


# Comparison of Acoustic Results (15 flights)



# Conservatism of Damage-Based Acoustics Results

- Conservative nature of damage-based acoustic results at higher frequency result of two factors
  - Maximax results contain more frequency smoothing due to third octave band SPL averaging within each overlapping time segment
    - Damage-based results computed at each oscillator frequency and converted to third octave SPL at end of processing
    - Present in all measurements
  - Higher frequency damage-based results controlled at some frequencies by transient characteristics (see plot)
    - Possibly due to data editing approach and treatment of dropouts
    - May be unique to this measurement



# Summary

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- Damage potential to hardware should be basis for flight and test equivalence
  - Not addressed by maximax approach
- SDOF oscillator response is a meaningful basis for comparison
  - Proportional to a modal response of test item
  - Damage potential due to fatigue accumulation, in addition to peak response, considered
- Large degree of over-conservatism in spectral peak values avoided
  - Avoid band-splitting during qualification testing as a result of excessively high overall grms
  - Avoid unnecessary re-qualification or vibration reduction measures resulting from results on early missions

## Summary (cont.)

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- Comparison of results available for statistically meaningful sets of Titan IVA vibration and acoustic measurements
- Applications
  - Assess adequacy of past qualification given new environmental data
  - Develop new test requirements
- Method to be available in VISPERS

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# Backup

# Why Results Not Always Dominated by Largest Q

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- Proportionality between  $Q$  and SDOF oscillator response differs depending on type of flight input
  - Random:  $A_{\max} \propto \sqrt{Q}$
  - Sinusoidal:  $A_{\max} \propto Q$
  - Transient: Relatively insensitive to  $Q$
- Stationary random test always inversely proportional to  $Q$

$$G = \frac{(A_{\max}^2 / Q)}{\pi f_n \ln(f_n T_0)}$$

- Random flight data: Relatively insensitive to  $Q$
- Sinusoidal flight data:  $G \propto Q$
- Transient flight data:  $G \propto 1/Q$